

Total No. of Questions : 10] [Total No. of Printed Pages : 4

Roll No.

EX-503(O)

B. E. (Fifth Semester) EXAMINATION, Dec., 2009

(Old Scheme)

(Electrical & Electronics Engg. Branch)

E. M. E. C. - II

[EX-503(O)]

Time : Three Hours

Maximum Marks : 100

Minimum Pass Marks : 35

Note : Attempt any five questions. Only one question to be answered from each Unit for 20 marks only.

Unit - I

1. (a) Derive e. m. f. equation of alternator and explain coil span factor and distribution factor. 10
- (b) The flux distribution curve of a smooth core, 50 Hz generator is $B = 10 \sin \theta + 2 \sin 3 \theta + 2 \sin 5 \theta + 2 \sin 7 \theta$ kilo-gauss when θ is measured from the neutral axis. The pole pitch is 35 cm, the core length 32 cm and the stator coil span four-fifth of the pole pitch. Determine the equation for the e. m. f. induced in one turn and its r. m. s. value. 10

P. T. O.

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Or

2. (a) Explain the O. C. and S. C. tests of an alternator. How regulation can be calculated by use at their results ? 10
- (b) A 3-phase, star connected, 1000 kVA, 11000 V alternator has rated current of 52.5 Amp. The a. c. resistance of the winding per phase is 0.45 ohm. The test results are given below : 10

O. C. Test : Field current = 12.5 Amp.

Voltage between lines = 422 Volts

S. C. Test : Field current = 12.5 Amp.

Line current = 52.5 Amp.

Determine the full-load voltage regulation of the alternator at :

(i) 0.8 p. f. lagging

(ii) 0.8 p. f. leading.

Unit-II

3. (a) Derive an expression for finding regulation of salient pole alternator using two reaction theory. Draw its phasor diagram. 10
- (b) A 3-phase synchronous generator has per phase a direct axis synchronous reactance of 1.0 P. U. and a quadrature axis synchronous reactance of 0.65 P. U. Draw a phasor diagram of the machine when operating at full-load at a p. f. of 0.8 lagging and estimate from there : 10

(i) The load angle

(ii) P. U. no-load e. m. f.

Neglect armature resistance.

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Or

4. (a) Two alternators are running in parallel and sharing a load in desired proportion. Explain what will happen if : 10
- (i) The excitations of alternator are changed while their prime mover inputs are fixed.
 - (ii) The prime mover inputs are varied while the excitations are kept fixed.
- (b) Two similar 400 V, 3-phase alternator share equal kW power delivered to a balanced 3-phase, 50 kW, 0.8 p. f. lagging load. If the power factor of one machine is 0.95 lagging, find the power factor and the current supplied by the other machine. 10

Unit – III

5. (a) Explain why the speed of a 3-phase synchronous motor remains constant at various loads when fed from a constant frequency. 10
- (b) A 3-phase synchronous motor absorbing 60 kW is connected in parallel with factory load of 240 kW having lagging power factor of 0.8. If the combined load has a p. f. of 0.9, what is the value of the leading KVAR supplied by the motor and at what power factor is it working ? 10

Or

6. (a) Draw a phasor diagram of a synchronous motor. Explain the effect of (i) change in excitation if load is constant, (ii) change in load if excitation is constant. 10
- (b) A 400 V, 10 HP, 3-phase synchronous motor has negligible armature resistance and synchronous reactance of 10 ohm per phase. Determine the minimum current and corresponding induced e. m. f. for full-load condition. Assume an efficiency of 85%. 10

P. T. O.

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Unit—IV

7. Draw the (i) basic two pole machine diagram and (ii) primitive machine diagram for synchronous machine with amoutrisserurs. Describe how these are obtained ? 20

Or

8. Explain the term 'invariance of power' as applied to electrical machines.

On what basis are the linear transformations carried out in electrical machines ? Explain. 20

Unit—V

9. (a) Draw and explain a typical torque speed characteristic of a reluctance motor. Compare a reluctance motor with an equivalent induction motor. 10

- (b) Explain the operating principle of linear induction motor. What is equivalent to synchronous speed of a rotating induction motor ? State its applications. 10

Or

10. (a) Describe the operation of a variable reluctance type stepper motor. What is microstepping ? 10

- (b) Describe the construction of PMDC motor. What are the advantages and disadvantages of permanent magnet d. c. motors compared with conventional d. c. shunt motor ? 10