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## EX - 602

## **B.E. VI Semester**

Examination, June 2013

# **Control Systems**

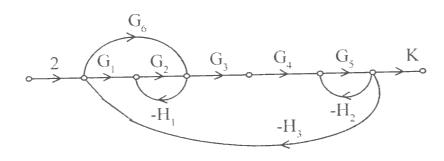
Time: Three Hours

Maximum Marks: 100

Minimum Pass Marks:35

*Note:* Total number of questions : 05. Attempt all questions.

- 1. a) Discuss the scientific approach of developing mathematical model of a system.
  - b) Obtain transfer function for a system, whose signal flow graph is shown below.



OR

Write short notes on:

- i) Error detectors
- ii) Open loop & closed loop system
- iii) Transfer function
- iv) Power amplifiers.

- . a) Differentiate between transient and steady state response. Illustrate all the time domain specification (transient & steady state) by suitable sketch.
  - b) Determine position, velocity and acceleration error for
    - i) Unit step,
    - ii) Unit ramp and
    - iii) Unit parabolic input, for the unity feedback control system with the open loop transfer function.

$$G(s) = \frac{K(1+0.5s)}{s^2(s^2+4s+5)}$$

#### OR

The state model of the system is given by

$$\begin{bmatrix} \dot{X} \end{bmatrix} = \begin{bmatrix} 0 & 11 \\ -12 & -7 \end{bmatrix} X + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(t)$$
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$$y = [-10 - 4]X + u(t)$$

Obtain state transition matrix and hence solve the equations for response 'y' when initial conditions are set to zero. 20

3. A unity feedback system has an open lop transfer function

$$G(s) = \frac{K(s+1)}{s(s+1)(s^2+2s+2)}$$
, by sketching root locus plot,

comment on the stability of the system. Obtain the value of K at which damping ratio = 0.5.

#### OR

Sketch the root locus of unity feedback system with open loop

function 
$$G(s) = \frac{K}{s(s+2)(s+3)(s+5)}$$
. Explain all the steps

clearly and marks all salient points on root locus. 20

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4. For a unity feedback system having open loop transfer function

$$G(s) = \frac{24(1+s)(1+0.2s)}{s(1+3s)(0.5s+1)(0.1s+1)}$$

Draw the Bode plots and determine gain margin and phase margin.

### OR

- a) Define & explain gain margin and phase margin with suitable example.
- b) Explain and construct polar plot for 10

$$G(s) = \frac{1}{s(0.2s+1)(0.05s+1)}$$

- 5. Discuss the step by step procedure for designing of 20
  - i) Phase lead compensator
  - ii) Phase lag compensator, and
  - iii) Phase lag-lead compensator.

### OR

Design a suitable compensator for a unity feedback system

with transfer function  $G(s) = \frac{16}{s(2s+1)(s+10)}$  to provide the phase margin of at least 45° and steady state error = 1%